

# 8324S006

Lo-Cog® DC Motor



Assembly Data	Symbol	Units	Value	
Reference Voltage	E	V	24	
No-Load Speed	S <sub>NL</sub>	rpm (rad/s)	10,158	(1064)
Continuous Torque (Max.) <sup>1</sup>	T <sub>C</sub>	oz-in (N-m)	2.6	(1.8E-02)
Peak Torque (Stall) <sup>2</sup>	T <sub>PK</sub>	oz-in (N-m)	17	(1.2E-01)
Weight	W <sub>M</sub>	oz (g)	5.8	(165)
Motor Data				
Torque Constant	K <sub>T</sub>	oz-in/A (N-m/A)	3.09	(2.18E-02)
Back-EMF Constant	K <sub>E</sub>	V/krpm (V/rad/s)	2.29	(2.18E-02)
Resistance	R <sub>T</sub>	Ω	4.33	
Inductance	L	mH	2.34	
No-Load Current	I <sub>NL</sub>	A	0.18	
Peak Current (Stall) <sup>2</sup>	I <sub>P</sub>	A	5.54	
Motor Constant	K <sub>M</sub>	oz-in/√W (N-m/√W)	1.49	(1.05E-02)
Friction Torque	T <sub>F</sub>	oz-in (N-m)	0.35	(2.5E-03)
Rotor Inertia	J <sub>M</sub>	oz-in-s <sup>2</sup> (kg-m <sup>2</sup> )	2.3E-04	(1.6E-06)
Electrical Time Constant	τ <sub>E</sub>	ms	0.54	
Mechanical Time Constant	τ <sub>M</sub>	ms	14.7	
Viscous Damping	D	oz-in/krpm (N-m-s)	0.020	(1.4E-06)
Damping Constant	K <sub>D</sub>	oz-in/krpm (N-m-s)	1.6	(1.1E-04)
Maximum Winding Temperature	θ <sub>MAX</sub>	°F (°C)	311	(155)
Thermal Impedance	R <sub>TH</sub>	°F/watt (°C/watt)	70.5	(21.4)
Thermal Time Constant	τ <sub>TH</sub>	min	10.7	
Gearbox Data				
Encoder Data				

**Included Features**

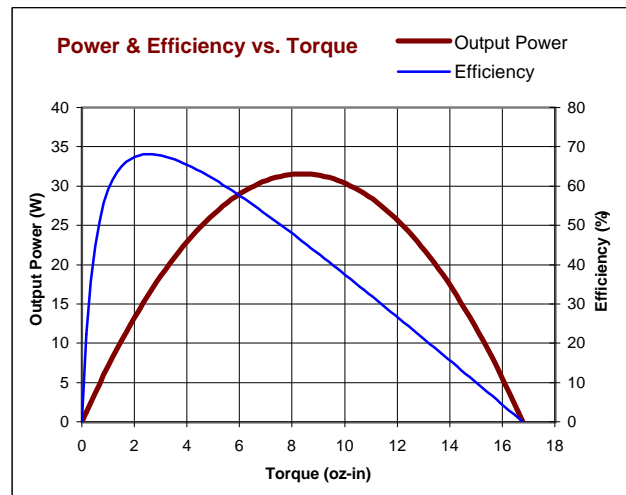
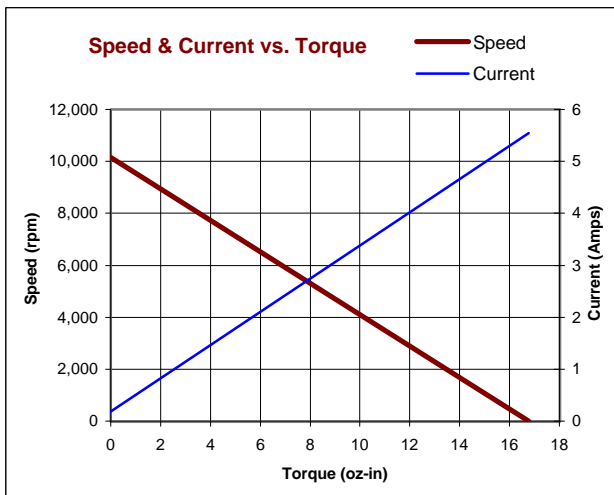
- 2-Pole Stator
- Ceramic Magnets
- Heavy-Gauge Steel Housing
- 7-Slot Armature
- Silicon Steel Laminations
- Stainless Steel Shaft
- Copper-Graphite Brushes
- Diamond Turned Commutator
- Motor Ball Bearings

---

**Customization Options**

- Alternate Winding
- Sleeve or Ball Bearings
- Modified Output Shaft
- Custom Cable Assembly
- Special Brushes
- EMI/RFI Suppression
- Spur or Planetary Gearbox
- Special Lubricant
- Optional Encoder
- Fail-Safe Brake

1 - Specified at max. winding temperature at 25°C ambient without heat sink. 2 - Theoretical values supplied for reference only.

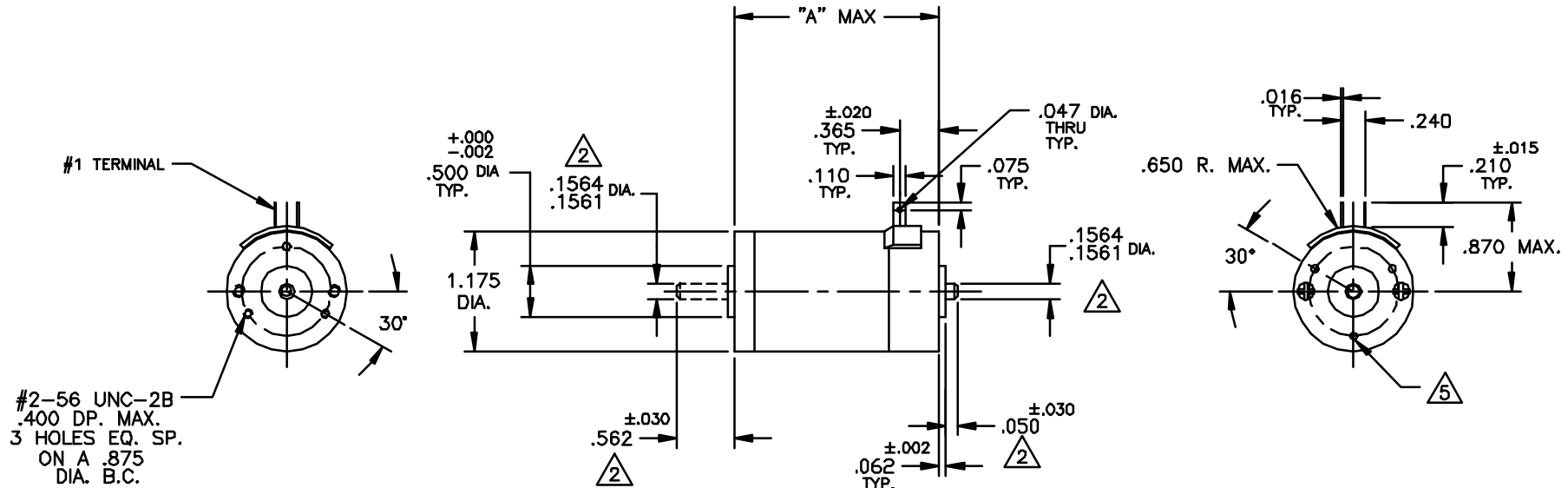


All values are nominal. Specifications subject to change without notice. Graphs are shown for reference only.

© 2001 Pittman.

NOTICE: CONFIDENTIAL PROPRIETARY INFORMATION THIS PRINT CONTAINS IDEAS, INFORMATION, AND INTELLECTUAL PROPERTY WHICH ARE THE EXCLUSIVE PROPERTY OF PITTMAN, DIVISION OF PENN ENGINEERING & MANUFACTURING CORP. RECIPIENT MUST KEEP THE INFORMATION DISCLOSED HEREIN CONFIDENTIAL AND RECIPIENT IS EXPRESSLY PROHIBITED FROM COPYING OR PUBLICATION OF THIS PRINT EXCEPT TO OTHERS IN THEIR ORGANIZATION ON A NEED-TO-KNOW BASIS

REVISIONS				
LTR	DESCRIPTION	DRFT/ENGR	DATE	APPR
F	REDRAWN, UPDATED TO CURRENT STDS.	KUH/KUH	12/6/95	JRM
G	CHANGED 2.328 TO 2.378	TN/TN	5/24/00	JRM
H	REMOVED "TIN" FROM NOTE 4	EWS/EWS	1/21/00	JRM
J	DIM .016 WAS .020	TMG/TMG		



NOTES:

- SHAFT ROTATION IS CW, WHILE VIEWING THE MOUNTING END, WITH POSITIVE VOLTAGE (+) APPLIED TO THE #1 TERMINAL.
- ALL SHAFT DIMENSIONS NOTED ARE STANDARD (10-754-00). FOR ALL OTHER SHAFT CONFIGURATIONS, REFER TO DATA SHEET FOR PART NUMBERS.
- BALL BEARINGS: PRELOAD PER P-107; SLEEVE BEARINGS; .015 MAX ENDPLAY.
- TERMINALS ARE PLATED FOR SOLDERING.
- OPTIONAL REAR MOUNTING PATTERN-#2-56 UNC-2B, .250 DP. MAX, 3 HOLES EQ. SP. ON A .875 DIA B.C.

2.378	83X4
2.128	83X3
2.003	83X2
"A" MAX	MODEL NO.

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES		FILE: 150\26		
TOLERANCES ARE:		DRAFTED BY KUH DATE 1DEC95		
FRACTION ±1/64	DECIMAL .XX ±.015	ENGINEERED BY KUH DATE 1DEC95	<b>TITLE:</b> OUTLINE & MOUNTING DIMENSIONS 83XX SERIES MOTORS	
ANGLES ±1°	XX ±.010	APPROVED BY JRM DATE 12/6/95		
BREAK ALL SHARP EDGES		NEXT ASSY:	<b>DWG. NO.</b> 150-26 <b>REV.</b> J	
MATERIAL:		USED ON:		
FINISH:		SCALE: NONE	<b>SHEET</b> 1 OF 1	